

1st Asian-Pacific Summer School on Formal Methods

Course 11: Hoare Logic with Pointers

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CEA List

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Summary

Functional Arrays

Aliasing

Memory models

Conclusion



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Conclusion

```
(long n)
{ for (i = 0; i < n; i++)
  C[i] = 0;
  tmp2 = 0;
  // ...
}
```

```
tmp2[i] = (i < (N-1) ? tmp1[i] : 0); // Then the second pass looks like the first one:
tmp1[i] = 0; k = 0; k++ tmp1[i][k] = mc2[i][k] * tmp2[k]; // The [i][k] coefficient of the matrix product MC2*TMP2, that is, *MC2*(TMP1) = MC2*(MC1*M1) = MC2*M1*(MC1 * M1) = 1 * tmp1[i][k] >= 1. // Final rounding: tmp2[i][k] is now represented on 9 bits. *if (tmp1[i][k] < -256) tmp2[i][k] = -256; else if (tmp1[i][k] > 255) tmp2[i][k] = 255; else tmp2[i][k] = tmp1[i][k];
```



- ▶ Hoare triples $\{P\}s\{Q\}$, meaning “*If we enter statement s in a state verifying P , the state after executing s will verify Q* ”.
- ▶ Function contracts, pre- and post-conditions.
- ▶ Weakest pre-condition calculus and program verification.
- ▶ The *Why* language.



Memory update

- ▶ in “classical” Hoare logic, variables are manipulated directly
- ▶ What happens if we add pointers, arrays, structures?

Example

```
int x[2];

/*@ ensures x[0]==0 &&
           x[1] == 1;*/

int main () {
    int i = 0;
    x[] = i;
    i=i+1;
    x[] = i;
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$x_0 == 0 \wedge x_1 == 1$



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$x_0 == 0 \wedge i + 1 == 1$



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int main () {  
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    x[i] = i;  
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$x_0 == 0 \wedge x_1 == 1$



Memory update

- ▶ in “classical” Hoare logic, variables are manipulated directly
- ▶ What happens if we add pointers, arrays,

$(i + 1 == 0 \Rightarrow$
 $(i + 1 == 0 \wedge x_1 == 1)) \wedge$
 $(i + 1 == 1 \Rightarrow$
 $(x_0 == 0 \wedge i + 1 == 1))$

Example

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int x[2];
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/*@ ensures x[0]==0 &&  
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int main () {  
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(long n)
{ for (i = 0; i < n; i++)
  C[i] = i;
  tmp2 = ...
  // ...
}
```

```
tmp2[i] = (i <= n/2 ? tmp1[i] : tmp1[n-i]); // Then the second pass looks like the first one:
tmp1[i] = 0; k = 0; k++ tmp1[i][k] = mc2[i][k] * tmp2[k]; // The [i][k] coefficient of the matrix product MC2*TMP2, that is, *MC2*(TMP1) = MC2*(MC1*M1) = MC2*M1*MC1
i = i+1; tmp1[i][0] >= 1; // Final rounding: tmp2[i][0] is now represented on 9 bits. *if (tmp1[i][0] < -256) m2[i][0] = -256; else if (tmp1[i][0] > 255) m2[i][0] = 255; else m2[i][0] = tmp1[i][0];
```



Operations

```
type 'a farray
logic select: 'a farray, int -> 'a
logic store: 'a farray, int, 'a -> 'a farray
```

Axioms

```
axiom select_store_eq:
forall a: 'a farray. forall i: int. forall v: 'a.
  select(store(a,i,v),i) = v
axiom select_store_neq:
forall a: 'a farray. forall i,j: int. forall v: 'a.
  i <> j ->
    select(store(a,i,v),j) = select(a,j)
```



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Correspondence

- ▶ array assignment is represented with store
- ▶ array access is represented with select

Example

```
int x[2];

/*@ ensures x[0]==0 &&
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int main () {
    int i = 0;
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    int i = 0;
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```

$\text{access}(x, 0) == 0 \wedge \text{access}(x, 1) == 1$



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- ▶ array access is represented with select

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```
int x[2];

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```

$\text{access}(\text{store}(x, i + 1, i + 1), 0) == 0 \wedge \dots$



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int x[2];

/*@ ensures x[0]==0 &&
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```

$\text{access}(\text{store}(\text{store}(x, i, i), i + 1, i + 1), 0) == 0 \wedge \dots$



Up to now our arrays are infinite: we can access or update any cell.

- ▶ Each array has a length
- ▶ select and store have to be guarded
- ▶ Use imperative arrays, *i.e.* references to functional arrays

Length

```
logic length: 'a farray -> int
axiom length_pos: forall a: 'a farray. length(a) >= 0
axiom store_length:
forall a: 'a farray. forall i: int. forall v: 'a.
length(store(a,i,v)) = length(a)
```



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```



Guarded accesses

parameter select_:

```
a: 'a farray ref -> i: int ->
{ 0 <= i < length(a) }
'a reads a
{ result = select(a,i) }
```

parameter store_:

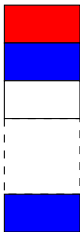
```
a: 'a farray ref -> i: int -> v: 'a ->
{ 0 <= i < length(a) }
unit writes a
{ a = store(a@,i,v) }
```



Description

Let x be an array whose elements are either BLUE, WHITE, or RED. We want to sort x 's elements, so that all BLUE are at the beginning, WHITE in the middle, and RED at the end.

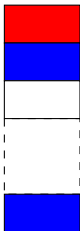
initial state



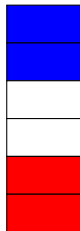
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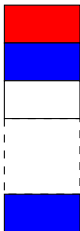
final state



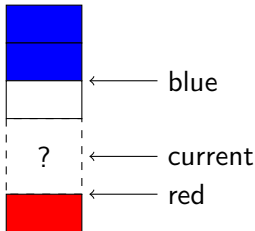
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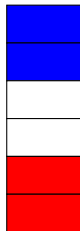
initial state



processing



final state



```
typedef enum { BLUE, WHITE, RED } color;

void dutch(color a[], int length) {
    int blue = 0, current = 0, red = length - 1;
    while (current < red) {
        switch (a[current]) {
            case BLUE : a[current]=a[blue]; a[blue]=BLUE;
                        white++; current++; break;
            case WHITE: current++; break;
            case RED   : red--; a[current]=a[red];
                        a[red]=RED; break;
        }
    }
}
```



```

type color
logic BLUE,WHITE,RED: color

axiom is_color: forall c: color.
    c = BLUE or c = WHITE or c = RED

parameter eq_color: c1:color -> c2:color ->
  {} bool { if result then c1 = c2 else c1 <> c2 }

```



logic monochrome:

color farray, **int**, **int**, color \rightarrow **prop**

axiom monochrome_def_1:

forall a: color farray. **forall** low,high: **int**.

forall c: color.

monochrome(a,low,high,c) \rightarrow

forall i:**int**. low \leq i<high \rightarrow select(a,i) = c

axiom monochrome_def_2:

forall a: color farray. **forall** low,high: **int**.

forall c: color.

(**forall** i:**int**. low \leq i<high \rightarrow select(a,i) = c) \rightarrow

monochrome(a,low,high,c)



```
let flag = fun (t: color farray ref) ->
begin
  let blue = ref 0 in
  let current = ref 0 in
  let red = ref (length !t) in
  while !current < !red do
    let c = select_ t !current in
    if (eq_color c BLUE) then begin
      store_ t !current (select_ t !blue);
      store_ t !blue BLUE;
      blue:=!blue+1;
      current:=!current + 1
    end
```



...

```

else if (eq_color c WHITE) then
  current:=!current + 1
else begin
  red:=!red-1;
  store_ t !current (select_ t !red);
  store_ t !red RED
end
done
end

```



No pre-condition

Post-condition:

```
{ exists blue: int. exists red: int.  
  monochrome(t,0,blue,BLUE) and  
  monochrome(t,blue,red,WHITE) and  
  monochrome(t,red,length(t),RED)  
}
```



Don't forget the loop invariant

```
{ invariant
  0<=blue and blue <= current and
  current <= red and red <= length(t) and
  monochrome(t,0,blue,BLUE) and
  monochrome(t,blue,current,WHITE) and
  monochrome(t,red,length(t),RED)
}
```



Is the program correct?

All proof obligations are discharged by alt-ergo:
gwhy dutch.why

Further specification

Currently, we have only proved that at the end we have a dutch flag. Other points remain:

- Do we have the same number of blue (resp. white and red) cells than at the start of the function?



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```
(long no
[ for ii <=
C1); if (0)
tmp2 =
st of the
```

```
tmp2[0] = (t <= 0 ? (N-1) - t) : t; else if (tmp1[0] >= 0) { t <= (N-1) - t; tmp2[0] = (t <= (N-1) - t) ? t : (N-1) - t; } else tmp2[0] = tmp1[0]; /* Then the second pass looks like the first one: */ for (k = 0; k < 8; k++) tmp1[0][k] += mc2[0][k] * tmp2[k][0]; /* The [i][j] coefficient of the matrix product MC2*TMP2, that is, *MC2*[t](TMP1) = MC2*[t](MC1*M1) = MC2*M1[t](MC1) + ... + MC2*M1[7](MC1) = 1 * tmp1[0][0] + ... + 1 * tmp1[7][0] >= 1. */ Final rounding: tmp2[0][0] is now represented on 9 bits. *if (tmp1[0][0] < -256) m2[0][0] = -256; else if (tmp1[0][0] > 255) m2[0][0] = 255; else m2[0][0] = tmp1[0][0];
```



Assignment Rule

Arrays are not the only objects which reflects poorly in the logic.
The assignment rule in Hoare logic:

$$\{P[x \leftarrow e]\} x = e \{P\}$$

contains implicit assumptions:

- ▶ Expressions e are shared between the original language and the logic
- ▶ We can always find a unique location x which is modified (no alias)

Examples of Problematic Constructions

- ▶ Pointers
- ▶ Structures

▶ Casts



- ▶ Pointer \sim base address + index
- ▶ Must take care of variables whose address is taken

Example

```
int x;
/*@ ensures
 *p == \old(*p) + 1; */
void incr (int* p)
{ (*p)++ }
```

```
parameter x: int farray ref
let incr =
fun (p: int farray ref) ->
{ length(p) >= 1 }
  store_ p 0
    ((select_ p 0)+1)
{ select(p,0) =
  select(p@,0) + 1
  and length(p)=length(p@)
}
```



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  and length(p)=length(p@)
}
```



```
/*@ ensures x == 1; */
int main ()
{incr(&x);
 return x}
```

```
let main = fun (_:unit) ->
{ length(x) = 1 and
  select(x,0) = 0 }
begin
  incr x;
  select_ x 0
end
{ length(x) = 1 and
  select(x,0) = 1 }
```

Demo



Position of the Problem

In the previous example, we only had one pointer. In practice, programs use usually more than that. What happens if two pointers refer to the same location?

Example

```
/*@ ensures *p == \old(*p + 1) &&
           *q == \old(*q + 1); */

void incr2(int* p, int* q) { (*p)++; (*q)++ }

int x;

/*@ ensures x == 1; */

int main () { incr2(&x,&x); return 0 }
```



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In the previous example, we only had one pointer. In practice, programs use usually more than that. What happens if two pointers refer to the same location?

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```
/*@ ensures *p == \old(*p + 1) &&
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void incr2(int* p, int* q) { (*p)++; (*q)++ }
int x;
/*@ ensures x == 1; */
int main () { incr2(&x,&x); return 0 }
```



Position of the Problem

In the previous example, we only had one pointer. In practice, programs use usually more than that. Is it possible to know if this is true only if p and q refer to the same location?

Example

```
/*@ ensures *p == \old(*p + 1) &&
           *q == \old(*q + 1); */
void incr2(int* p, int* q) { (*p)++; (*q)++ }
int x;
/*@ ensures x == 1; */
int main () { incr2(&x,&x); return 0 }
```

this is true only if p and q are distinct



An erroneous why translation

```
parameter x: int farray ref
let incr2 = fun (p: int farray ref) ->
fun (q: int farray ref) ->
begin store_ p 0 ((select_ p 0)+1);
  store_ q 0 ((select q 0)+1) end
{ select(p,0) = select(p@,0) + 1 and
  select(q,0) = select(q@,0) + 1}
let main = fun (_:unit) -> { select(x,0) = 0 }
begin let _ = incr2 x x in select_ x 0 end
{ select(x,0) = 1 }
```

result

Computation of VCs...

File "pointer2.why", line 28, characters 22-23:

Application to x creates an alias



An erroneous why translation

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parameter x: int farray ref
let incr2 = fun (p: int farray ref) ->
fun (q: int farray ref) ->
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  store_ q 0 ((select q 0)+1) end
{ select(p,0) = select(p@,0) + 1 and
  select(q,0) = select(q@,0) + 1}
let main = fun (_:unit) -> { select(x,0) = 0 }
begin let _ = incr2 x x in select_ x 0 end
{ select(x,0) = 1 }
```

error is here

result

Computation of VCs...

File "pointer2.why", line 28, characters 22-23:

Application to x creates an alias



- ▶ Extension of Hoare logic dealing allowing to deal with the heap
- ▶ introduced by O'Hearn and Reynolds in 2001-2002
- ▶ new logic operators:
 - ▶ $l \mapsto v$: the heap contains a single location l with value v
 - ▶ $e_1 * e_2$: the heap is composed of two **distinct** parts, verifying e_1 and e_2 respectively

Example

Pre-condition for `incr2`:

$$\exists n, m : int. p \mapsto n * q \mapsto m$$



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Pre-condition for `incr2`:

$$\exists n, m : \text{int}. p \mapsto n * q \mapsto m$$



Most Hoare logic inference rules apply to separation logic. A new rule indicates that it is always possible to extend the heap:

$$\frac{\{P\}s\{Q\}}{\{P * R\}s\{Q * R\}}$$

provided the free variables of R are not modified by s .



- ▶ Separation logic is a very powerful formalism to deal explicitly with memory.
- ▶ Very few tools deal directly with separation logic
- ▶ Some of its concepts are incorporated in memory models



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```
(long n)
{ for (i = 0; i < n; i++)
  C[i] = 0;
  tmp2 = ...
  // ...
}
```

```
tmp2[i] = (i < (N-1) ? tmp1[i] : 0); // Then the second pass looks like the first one:
tmp1[i] = 0; k = 0; k++ tmp1[i][k] = mc2[i][k] * tmp2[k]; // The [i][k] coefficient of the matrix product MC2*TMP2, that is, *MC2*(TMP1) = MC2*(MC1*M1) = MC2*M1*(MC1 * M1) = 1 * tmp1[i] >= 1. // Final rounding: tmp2[i] is now represented on 9 bits. *if (tmp1[i] < -256) tmp2[i] = -256; else if (tmp1[i] > 255) tmp2[i] = 255; else tmp2[i] = tmp1[i];
```



Presentation

In order to deal with pointers, we have to represent somehow the whole memory state of the program in the logic. This is called a **memory model**.

A first attempt

- ▶ See the memory as one big array, with pointers as indices.
- ✓ very close to the concrete execution.
- ✓ allows to represent all program constructions.
- ✗ each store can potentially modify something anywhere
- ✗ in practice formulas quickly become untractable.



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In order to deal with pointers, we have to represent somehow the whole memory state of the program in the logic. This is called a **memory model**.

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- ▶ See the memory as one big array, with pointers as indices.
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In order to overcome the scalability issues of the memory-as-array model, more abstract models can be used.

- ▶ Split the memory in distinct, smaller arrays, for locations which are known not to overlap.
- ▶ For programs with structures, we use an array per field ($x \rightarrow a$ and $y \rightarrow b$ are necessarily distinct).
- ▶ Can be extended to distinguish `int` and `float`, `int` and `struct`
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- It is possible to go beyond the Burstall-Bornat partition by using some static analysis to identify regions which do not overlap
- Used by the Jessie tool to refine its model
- New preconditions (separation of pointers) that need to be checked

example

```
int a[2];
void incr2(int* x, int* y) { ... }

int main() {
    incr2(&a[0], &a[1]);
    return 0;
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pre condition: *separated(x, y)*



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separated(&a[0], &a[1]) holds



Summary

Functional Arrays

Aliasing

Memory models

Conclusion

```
(long n)
{ for (i = 0; i < n; i++)
  C[i] = i;
  tmp2 = ...
  // ...
}
```

```
tmp2[0] = 0; for (i = 1; i < n; i++) tmp2[i] = tmp2[i-1] + 1; // Then the second pass looks like the first one:
tmp2[0] = 0; for (i = 1; i < n; i++) tmp2[i] = tmp2[i-1] + 1; // The [i] coefficient of the matrix product MC2*TMP1, that is, *MC2*(TMP1) = MC2*(MC1*M1) = MC2*M1*(MC1) = ...
i = 1; tmp2[0] = 0; // Final rounding: tmp2[0] is now represented on 9 bits. *if (tmp2[0] < -256) tmp2[0] = -256; else if (tmp2[0] > 255) tmp2[0] = 255; else tmp2[0] = tmp2[0];
```



- ▶ Dealing with memory can be tricky
- ▶ Functional arrays play a central role
- ▶ Aliases and separation properties
- ▶ Need for memory models
- ▶ How to do that in practice: see tomorrow

(long no
[for 0 < i < n
C1); if (0 < i
tmp2 = m
of the

tmp2[j] = (t <= 0 ? 0 : t); else if (tmp1[j] >= 0) { t <= 0 ? 0 : t; } else tmp2[j] = tmp1[j]; /* Then the second pass looks like the first one: */
tmp1[0] = 0; k = 0; k++ tmp1[k] = mc2[0][k] * tmp2[k][0]; /* The [i][j] coefficient of the matrix product MC2*TMP2, that is: *MC2*[i][TMP1] = MC2*[i][MC1*M1] = MC2*[i][MC1] * M1[i][k] = 1 * tmp1[0][k] >= 1. */ Final rounding: tmp2[0][0] is now represented on 9 bits: *if (tmp1[0][0] < -256) tmp2[0][0] = -256; else if (tmp1[0][0] > 255) tmp2[0][0] = 255; else tmp2[0][0] = tmp1[0][0];

