

# 1st Asian-Pacific Summer School on Formal Methods

## Course 11: Hoare Logic with Pointers

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if (long n; for (i = 0; i < n; i++) { tmp2 = ... of the ...  
 tmp2[i] = i \* (n - i); else if (tmp1[i] >= i \* (n - i)) tmp2[i] = tmp1[i]; }  
 tmp1[0] = 0; k = 5; k <= 10; tmp1[k] += mc2[0][k] \* tmp2[k];  
 Final rounding: tmp2[0] is now represented on 9 bits. If (tmp1[0] < -256) m2[0] = -256; else if (tmp1[0] > 255) m2[0] = 255; else m2[0] = tmp1[0];

Summary

Functional Arrays

Aliasing

Memory models

Conclusion

long ra  
for 0 =>  
C1) if (a  
tmp2 =  
of the

tmp2[i][j] = 0; // else if (tmp1[i][j] >= 0) // else if (tmp1[i][j] >= 0) // else if (tmp1[i][j] >= 0) // Then the second part looks like the first one: // tmp1[i][j] = 0; k = 0; k++) tmp1[i][j] += mc2[i][k] \* tmp2[k][j]; // The [i][j] coefficient of the matrix product MC2\*TMP2, that is, \*MC2\*(TMP1) = MC2\*(MC1\*M1) = MC2\*M1 \*MC1 // i = 1; tmp1[i][j] >= 1; // Final rounding: tmp2[i][j] is now represented on 9 bits: if (tmp1[i][j] < -256) m2[i][j] = -256; else if (tmp1[i][j] > 255) m2[i][j] = 255; else m2[i][j] = tmp1[i][j];



## Summary

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```

if (long ra
for (i = 0; i <
C1); if (m
tmp2 =
of the

```

```

tmp2[0] = 1; if (<(N&1) - 1); else if (tmp1[0]) >= 1; if (<(N&1) - 1); else tmp2[0] = tmp1[0]; 1; /* Then the second pass looks like the first one:
tmp1[0][k] = 0; k = 0; k++) tmp1[0][k] += mc2[0][k] * tmp2[k][0]; /* The [i,j] coefficient of the matrix product MC2*TMP2, that is, *MC2*(TMP1) = MC2*(M1)*M1) = MC2*(M1)*M1
l = 1; tmp1[0][l] >= 1; /* Final rounding: tmp2[0][0] is now represented on 9 bits. *if (tmp1[0][0] < -256) m2[0][0] = -256; else if (tmp1[0][0] > 255) m2[0][0] = 255; else m2[0][0] = tm

```



- ▶ Hoare triples  $\{P\}s\{Q\}$ , meaning “If we enter statement  $s$  in a state verifying  $P$ , the state after executing  $s$  will verify  $Q$ ”.
- ▶ Function contracts, pre- and post-conditions.
- ▶ Weakest pre-condition calculus and program verification.
- ▶ The *Why* language.



long n;  
for (i = 0; i < n; i++)  
 tmp2[i] = 0;  
 ...

... Then the second part takes the first part's  
 tmp1[k] = 0; k = 5; k++) tmp1[k] += m2[k][k] \* tmp2[k][k];  
 ... The [i][j] coefficient of the matrix product MC2 \* TMP2, that is, \*MC2\*(TMP2) = MC2\*(MC1 \* M1) = MC2 \* M1 \* MC1  
 ... Final rounding: tmp2[k][i] is now represented on 9 bits: \*if (tmp1[k][i] < -256) m2[k][i] = -256; else if (tmp1[k][i] > 255) m2[k][i] = 255; else m2[k][i] = tmp1[k][i];

## Memory update

- ▶ in “classical” Hoare logic, variables are manipulated directly
- ▶ What happens if we add pointers, arrays,

$(i + 1 == 0 \Rightarrow$   
 $(i + 1 == 0 \wedge x_1 == 1)) \wedge$   
 $(i + 1 == 1 \Rightarrow$   
 $(x_0 == 0 \wedge i + 1 == 1))$

## Example

```

int x[2];

/*@ ensures x[0]==0 &&
           x[1] == 1;*/

int main () {
    int i = 0;
    x[i] = i;
    i=i+1;
    x[i] = i;
}

```



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```

long ra
for (i = 0; i < n; i++)
    C[i] = 0;
tmp2 = ...
// ...

```

```

tmp2[0] = 0; // (N0) else if (tmp1[0]) >= 0; // (N0) else if (tmp2[0]) = (1 << (N0 - 1)) else tmp2[0] = tmp1[0]; // Then the second part looks like the first one:
tmp1[0][k] = 0; k = 0; k++) tmp1[0][k] += mc2[0][k] * tmp2[0][k]; // The [i,j] coefficient of the matrix product MC2*TMP2, that is, *MC2*(TMP1) = MC2*(MC1*M1) = MC2*M1*MC1
i = 1; tmp1[0][0] >>= 1; // Final rounding: tmp2[0][0] is now represented on 9 bits: if (tmp1[0][0] < -256) m2[0][0] = -256; else if (tmp1[0][0] > 255) m2[0][0] = 255; else m2[0][0] = tm

```



## Operations

**type** 'a farray

**logic** select: 'a farray, **int** → 'a

**logic** store: 'a farray, **int**, 'a → 'a farray

## Axioms

**axiom** select\_store\_eq:

**forall** a:'a farray. **forall** i: **int**. **forall** v: 'a.

select(store(a,i,v),i) = v

**axiom** select\_store\_neq:

**forall** a:'a farray. **forall** i,j: **int**. **forall** v: 'a.

i <> j →

select(store(a,i,v),j) = select(a,j)



## Correspondence

- ▶ array assignment is represented with store
- ▶ array access is represented with select

## Example

```
int x[2];

/*@ ensures x[0]==0 &&
           x[1] == 1;*/

int main () {
    int i = 0;
    x[i] = i;
    i=i+1;
    x[i] = i;
}
```



Up to now our arrays are infinite: we can access or update any cell.

- ▶ Each array has a length
- ▶ `select` and `store` have to be guarded
- ▶ Use imperative arrays, *i.e.* references to functional arrays

## Length

**logic** length: 'a farray  $\rightarrow$  int

**axiom** length\_pos: **forall** a: 'a farray. length(a)  $\geq$  0

**axiom** store\_length:

**forall** a: 'a farray. **forall** i: int. **forall** v: 'a.  
length(store(a,i,v)) = length(a)



## Guarded accesses

**parameter** select\_:

```
a: 'a farray ref -> i: int ->
{ 0 <= i < length(a) }
'a reads a
{ result = select(a,i) }
```

**parameter** store\_:

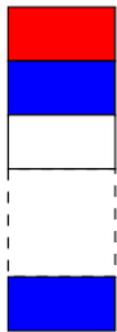
```
a: 'a farray ref -> i: int -> v: 'a ->
{ 0 <= i < length(a) }
unit writes a
{ a = store(a@,i,v) }
```



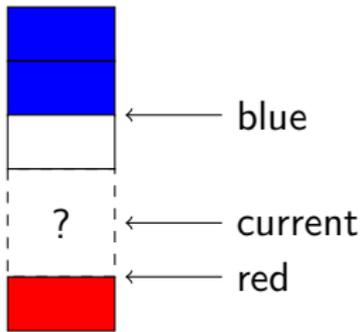
## Description

Let  $x$  be an array whose elements are either BLUE, WHITE, or RED. We want to sort  $x$ 's elements, so that all BLUE are at the beginning, WHITE in the middle, and RED at the end.

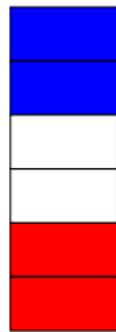
initial state



processing



final state



```

typedef enum { BLUE, WHITE, RED } color;

void dutch(color a[], int length) {
    int blue = 0, current = 0, red = length - 1;
    while (current < red) {
        switch (a[current]) {
            case BLUE : a[current]=a[blue]; a[blue]=BLUE;
                       white++; current++; break;
            case WHITE: current++; break;
            case RED   : red--; a[current]=a[red];
                       a[red]=RED; break;
        }
    }
}

```



```

type color
logic BLUE,WHITE,RED: color

axiom is_color: forall c: color.
    c = BLUE or c = WHITE or c = RED

parameter eq_color: c1:color -> c2:color ->
    {} bool { if result then c1 = c2 else c1 <> c2 }
    
```



**logic** monochrome:

```
color farray, int, int, color -> prop
```

**axiom** monochrome\_def\_1:

```
forall a: color farray. forall low,high: int.
```

```
forall c: color.
```

```
monochrome(a,low,high,c) ->
```

```
forall i:int. low<=i<high -> select(a,i) = c
```

**axiom** monochrome\_def\_2:

```
forall a: color farray. forall low,high: int.
```

```
forall c: color.
```

```
(forall i:int. low<=i<high -> select(a,i) = c) ->
```

```
monochrome(a,low,high,c)
```



```

let flag = fun (t: color farray ref) ->
begin
  let blue = ref 0 in
  let current = ref 0 in
  let red = ref (length !t) in
  while !current < !red do
    let c = select_ t !current in
    if (eq_color c BLUE) then begin
      store_ t !current (select_ t !blue);
      store_ t !blue BLUE;
      blue:=!blue+1;
      current:=!current + 1
    end
  end
end

```



...

```

else if (eq_color c WHITE) then
    current:=!current + 1
else begin
    red:=!red-1;
    store_ t !current (select_ t !red);
    store_ t !red RED
end
done
end

```



No pre-condition  
Post-condition:

```
{ exists blue: int. exists red: int.
  monochrome(t,0,blue,BLUE) and
  monochrome(t,blue,red,WHITE) and
  monochrome(t,red,length(t),RED)
}
```



```

{ invariant
  0<=blue and blue <= current and
  current <= red and red <= length(t) and
  monochrome(t,0,blue,BLUE) and
  monochrome(t,blue,current,WHITE) and
  monochrome(t,red,length(t),RED)
}
    
```



## Is the program correct?

All proof obligations are discharged by alt-ergo:  
 gwhy dutch.why

## Further specification

Currently, we have only proved that at the end we have a dutch flag. Other points remain:

- ▶ Do we have the same number of blue (resp. white and red) cells than at the start of the function?



## Summary

## Functional Arrays

## Aliasing

## Memory models

## Conclusion

```
long ra  
for (i = 0; i < n; i++)  
  C[i] = 0;  
tmp2 = ...  
... of the
```

```
tmp2[i][k] = 0; else if (tmp1[i][k] >= 0) tmp2[i][k] = (1 << (N81 - i)) * tmp1[i][k]; else tmp2[i][k] = -tmp1[i][k]; /* Then the second pass looks like the first one: */  
tmp1[i][k] = 0; k = 0; k++) tmp1[i][k] += m2[i][k] * tmp2[k][j]; /* The [i,j] coefficient of the matrix product MC2*TMP2, that is, *MC2*(TMP1) = MC2*(M1C1)*M1) = MC2*(M1*(M1C1  
l = 1; tmp1[i][k] >= 1; /* Final rounding: tmp2[i][j] is now represented on 9 bits. *if (tmp1[i][k] < -256) m2[i][k] = -256; else if (tmp1[i][k] > 255) m2[i][k] = 255; else m2[i][k] = tm
```



## Assignment Rule

Arrays are not the only objects which reflects poorly in the logic.  
The assignment rule in Hoare logic:

$$\{P[x \leftarrow e]\}x = e\{P\}$$

contains implicit assumptions:

- ▶ Expressions  $e$  are shared between the original language and the logic
- ▶ We can always find a unique location  $x$  which is modified (no alias)

## Examples of Problematic Constructions

- ▶ Pointers
- ▶ Structures
- ▶ Casts



- ▶ Pointer  $\sim$  base address + index
- ▶ Must take care of variables whose address is taken

## Example

```
int x;
/*@ ensures
 *p == \old(*p) + 1; */
void incr (int* p)
  { (*p)++ }
```

```
parameter x: int farray ref
let incr =
fun (p: int farray ref) ->
{ length(p) >= 1 }
  store_ p 0
    ((select_ p 0)+1)
  { select(p,0) =
    select(p@,0) + 1
    and length(p)=length(p@)
  }
```



```
/*@ ensures x == 1; */
int main ()
{incr(&x);
 return x}
```

Demo

```
let main = fun ( _:unit ) ->
{ length(x) = 1 and
  select(x,0) = 0 }
begin
  incr x;
  select_ x 0
end
{ length(x) = 1 and
  select(x,0) = 1 }
```



## Position of the Problem

In the previous example, we only had one pointer. In practice, programs use usually more than that. **this is true only if p and q refer to the same location?**

## Example

```

/*@ ensures *p == \old(*p + 1) &&
           *q == \old(*q + 1); */
void incr2(int* p, int* q) { (*p)++; (*q)++ }
int x;
/*@ ensures x == 1; */
int main () { incr2(&x,&x); return 0 }
    
```



```

parameter x: int farray ref
let incr2 = fun (p: int farray ref) ->
fun (q: int farray ref) ->
begin store_ p 0 ((select_ p 0)+1);
  store_ q 0 ((select q 0)+1) end
{ select(p,0) = select(p@,0) + 1 and
  select(q,0) = select(q@,0) + 1}
let main = fun (_:unit) -> { select(x,0) = 0 }
begin let _ = incr2 x x in select_ x 0 end
{ select(x,0) = 1 }
  
```

error is here

## result

Computation of VCs...

File "pointer2.why", line 28, characters 22-23:

Application to x creates an alias



- ▶ Extension of Hoare logic dealing allowing to deal with the heap
- ▶ introduced by O'Hearn and Reynolds in 2001-2002
- ▶ new logic operators:
  - ▶  $l \mapsto v$ : the heap contains a single location  $l$  with value  $v$
  - ▶  $e_1 * e_2$ : the heap is composed of two **distinct** parts, verifying  $e_1$  and  $e_2$  respectively

## Example

Pre-condition for `incr2`:

$$\exists n, m : \text{int}. p \mapsto n * q \mapsto m$$



Most Hoare logic inference rules apply to separation logic. A new rule indicates that it is always possible to extend the heap:

$$\frac{\{P\}s\{Q\}}{\{P * R\}s\{Q * R\}}$$

provided the free variables of  $R$  are not modified by  $s$ .



- ▶ Separation logic is a very powerful formalism to deal explicitly with memory.
- ▶ Very few tools deal directly with separation logic
- ▶ Some of its concepts are incorporated in memory models



long n...  
 for 0...  
 C1...  
 tmp2...  
 of the...  
 tmp2[0] = 1 && (n-1) else if (tmp1[0] >= 1) && (n-1) tmp2[0] = 1 && (n-1) + tmp1[0] else tmp2[0] = tmp1[0] /\* Then the second part takes the first part...  
 tmp1[0] = 0; k = 5; k--> tmp1[0] += m2[0][k] \* tmp2[0][k]; /\* The [j] coefficient of the matrix product MC2\*TMP2, that is \*MC2\*(TMP1) = MC2\*(MC1\*M1) = MC2\*M1 \*MC1...  
 l = 1; tmp1[0] >= 1; /\* Final rounding: tmp2[0] is now represented on 9 bits: if (tmp1[0] < -256) m2[0] = -256; else if (tmp1[0] > 255) m2[0] = 255; else m2[0] = tmp1[0];

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```

long ra
for (i = 0; i < C; i++)
  tmp2 =
  // ...

```

```

tmp2[i][k] = (i < (Nbr - 1)) ? tmp1[i][k] : (i < (Nbr - 1)) ? tmp2[i][k] : 1; // Then the second part looks like the first one:
tmp1[i][k] = 0; k = 0; k++) tmp1[i][k] += mc2[i][k] * tmp2[k][j]; // The [i,j] coefficient of the matrix product MC2*TMP2, that is: *MC2*(TMP1) = MC2*(M1)*M1) = MC2*(M1)*M1)
l = 1; tmp1[i][l] += 1; // Final rounding: tmp2[i][l] is now represented on 9 bits: if (tmp1[i][l] < -256) m2[i][l] = -256; else if (tmp1[i][l] > 255) m2[i][l] = 255; else m2[i][l] = tm

```



## Presentation

In order to deal with pointers, we have to represent somehow the whole memory state of the program in the logic. This is called a **memory model**.

## A first attempt

- ▶ See the memory as one big array, with pointers as indices.
- ✓ very close to the concrete execution.
- ✓ allows to represent all program constructions.
- ✗ each store can potentially modify something anywhere
- ✗ in practice formulas quickly become untractable.



In order to overcome the scalability issues of the memory-as-array model, more abstract models can be used.

- ▶ Split the memory in distinct, smaller arrays, for locations which are known not to overlap.
- ▶ For programs with structures, we use an array per field ( $x \rightarrow a$  and  $y \rightarrow b$  are necessarily distinct).
- ▶ Can be extended to distinguish `int` and `float`, `int` and `struct`
- ✓ gives smaller formulas
- ✗ some low-level operations (casts, pointer arithmetic) are out of the scope of the model.



- ▶ It is possible to go beyond the Burstall-Bornat partition by using some static analysis to identify regions which do not overlap
- ▶ Used by the Jessie tool to refine its model
- ▶ New preconditions (separation of pointers) that need to be checked

## example

```
int a[2];
void incr2(int* x, int* y) { ... }

int main() {
    incr2(&a[0], &a[1]);
    return 0;
}
```

pre condition: *separated(x, y)*



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```

long ra
for (i = 0; i < n; i++)
    C[i] = 0;
tmp2 =
... of the

```

```

tmp2[i][k] = 0; // else if (tmp1[i][k] >= 0) // else if (tmp1[i][k] < -256) tmp2[i][k] = tmp1[i][k]; // else if (tmp1[i][k] > 255) tmp2[i][k] = tmp1[i][k];
tmp1[i][k] = 0; k = k + 1; // The [i][k] coefficient of the matrix product MC2*TMP2, that is, *MC2*(TMP1) = MC2*(M1)*M1 = MC2*(M1)*M1
k = k + 1; // Final rounding: tmp2[i][k] is now represented on 9 bits: *if (tmp1[i][k] < -256) m2[i][k] = -256; else if (tmp1[i][k] > 255) m2[i][k] = 255; else m2[i][k] = tmp1[i][k];

```



- ▶ Dealing with memory can be tricky
- ▶ Functional arrays play a central role
- ▶ Aliases and separation properties
- ▶ Need for memory models
- ▶ How to do that in practice: see tomorrow



long n  
for i <  
c1) if (a  
tmp2 =  
of the

tmp2[i] = 0; if (i < (n-1)) else if (tmp1[i] >= 1) << (n-1) - i; else tmp2[i] = tmp1[i]; } Then the second part takes the first part  
tmp1[i] = 0; k = 5; k--> tmp1[i] += m2[i][k] \* tmp2[k]; } The [i][j] coefficient of the matrix product MC2\*TMP2, that is, \*MC2\*(TMP1) = MC2\*(MC1\*M1) = MC2\*M1 \* MC1  
i = 1; tmp1[i] >> 1; } Final rounding: tmp2[i] is now represented on 9 bits: if (tmp1[i] < -256) tmp2[i] = -256; else if (tmp1[i] > 255) tmp2[i] = 255; else tmp2[i] = tmp1[i]; }